

RESEARCH INTERESTS

My goal is to make programming social robots easy and approachable for interaction designers and end-user developers alike. I use **formal verification** to assist robot programmers reason about interaction social norms, **program synthesis** to assist programmers in implementing these interactions, and **program repair** to automatically fix these interactions.

EDUCATION

PhD	University of Wisconsin–Madison (UW–Madison), Madison, WI, USA Computer Sciences	2018-present
MSc	UW–Madison, Madison, WI, USA Computer Sciences	2016-2018
BS	University of Arizona (UA), Tucson, AZ, USA Double degree (hon) in computer science and physiology Minor in mathematics Summa cum laude	2011-2016

WORK & RESEARCH EXPERIENCE

Doctoral Research UW–Madison, Madison, WI, USA Computer Sciences Committee: Drs. Bilge Mutlu, Aws Albarghouthi, Maya Cakmak, and Kevin Ponto	2016-present
Research Intern Nokia Bell Labs, New Providence, NJ, USA (Virtual) Mentors: Drs. Martin Carroll, Kedar Namjoshi, Itai Segall	Summer 2021
Undergraduate Senior Thesis UW–Madison, Madison, WI, USA Computer Sciences Advisor: Dr. John Kececioğlu	2015-2016
Undergraduate Research UW–Madison, Madison, WI, USA Computer Sciences Advisors: Drs. E. Fiona Bailey and Joanna Masel	2013-2014

FELLOWSHIPS, HONORS, and AWARDS

Microsoft Dissertation Grant Awarded \$21,148 for dissertation research	2021
Cisco Graduate Student Fellowship Selected by the UW–Madison Computer Sciences Department	2021
Heidelberg Laureate Forum Invited to attend as a young researcher	2019
Best Paper Award UIST '18	2018
NSF Graduate Research Fellowship	2017
Advanced Opportunity Fellowship Selected by the UW–Madison Computer Sciences Department	2016

Excellence in Undergraduate Research Award Selected by the UA Department of Computer Science	2016
Galileo Circle Scholar Selected by the UA Department of Computer Science	2015
National Hispanic Scholar Selected by the National Hispanic Recognition Program	2011
Dean's List with Distinction Awarded during six semesters at UA	2011-2016

REFEREED FULL PAPERS

Porfirio, D., Stegner, L., Cakmak, M., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2021, May). Figaro: A Tabletop Authoring Environment for Human-Robot Interaction. In Proceedings of the 2021 CHI Conference on Human Factors in Computing Systems (pp. 1-15).

Porfirio, D., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2020, April). Transforming robot programs based on social context. In Proceedings of the 2020 CHI conference on human factors in computing systems (pp. 1-12).

Porfirio, D., Fisher, E., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2019, October). Bodystorming Human-Robot Interactions. In Proceedings of the 32nd Annual ACM Symposium on User Interface Software and Technology (pp. 479-491). ACM.

Porfirio, D., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2018, October). Authoring and verifying human-robot interactions. In The 31st Annual ACM Symposium on User Interface Software and Technology (pp. 75-86). ACM.

Xiong, K., McEntee, J. P., **Porfirio, D. J.**, & Masel, J. (2017). Drift barriers to quality control when genes are expressed at different levels. *Genetics*, 205(1), 397-407.

Shumway, K. R., **Porfirio, D. J.**, & Bailey, E. F. (2015). Phonation-related rate coding and recruitment in the genioglossus muscle. *Experimental brain research*, 233(7), 2133-2140.

REFEREED SHORT PAPERS

Porfirio, D., Cakmak, M., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2021, May). Interaction Templates: A Data-Driven Approach for Authoring Robot Programs. In 2021 12th Annual Workshop on Evaluation and Usability of Programming Languages and Tools (PLATEAU) (in press).

Porfirio, D., Sauppé, A., Albarghouthi, A., & Mutlu, B. (2019, March). Computational Tools for Human-Robot Interaction Design. In 2019 14th ACM/IEEE International Conference on Human-Robot Interaction (HRI) (pp. 733-735). IEEE.

TEACHING EXPERIENCE

Grandparents University Instructor Summers 2018-2019.
Co-organized social robotics lecture and lab sessions for children and their grandparents.

Teaching Assistant, UA Summer 2015
CSC 352, Systems Programming and Unix
Duties: holding office hours and grading programming assignments

Section Leader, UA Fall 2014 - Spring 2015
CSC 245, Introduction to Discrete Structures
CSC 227, Program Design and Development
Duties: teaching lab sessions, holding office hours, and grading assignments

REFeree SERVICES

Reviewer

2021 ACM Symposium on User Interface Software and Technology (UIST)
2021 AAAI Artificial Intelligence for Human-Robot Interaction (AI-HRI) Fall Symposium Series
2021 ACM/IEEE International Conference on Human-Robot Interaction (HRI) Late Breaking Reports
2021 ACM/IEEE International Conference on Human-Robot Interaction (HRI) PIONEERS Workshop
2020 ACM Transactions on Human-Robot Interaction (THRI)
2020 ACM/IEEE International Conference on Human-Robot Interaction (HRI) Alt.HRI

TECHNICAL SKILLS

Programming

Python, Golang, Java, Javascript, HTML, CSS, C#, C

Tools, Libraries, and Frameworks

ROS, Z3 Theorem Prover, PRISM Model Checker, NuSMV Model Checker, LaTeX, Git, OpenCV, D3.js, Matplotlib

Robot Platforms

Softbank Pepper, Softbank Nao, Temi, iRobot Create 2

Software

Illustrator, Premiere, Photoshop, Unity, Office